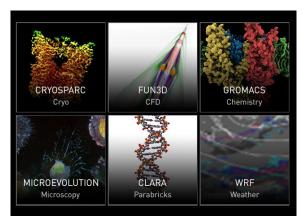
DrGPU: A Top-Down Profiler for GPU

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GPUs are Broadly Used for Acceleration























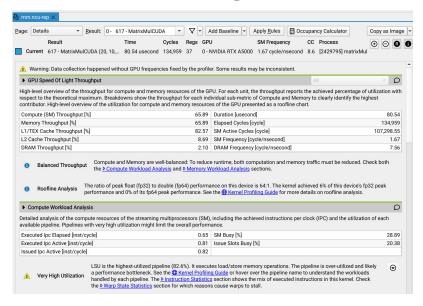


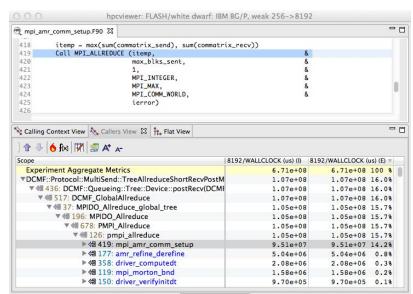


GPU Programming

```
Kernel definition
 global void VecAdd(float* A, float* B, float* C)
                                                         GPU Kernel
   int i = threadIdx.x;
   C[i] = A[i] + B[i];
int main()
                                                    # of GPU threads
   // Kernel invocation with N threads
                                                    1 warp = 32 threads
   N = 1024
   VecAdd<<<1, N>>>(A, B, C);
```

Existing GPU Performance Tools





NVIDIA Nsight Compute

HPCToolkit

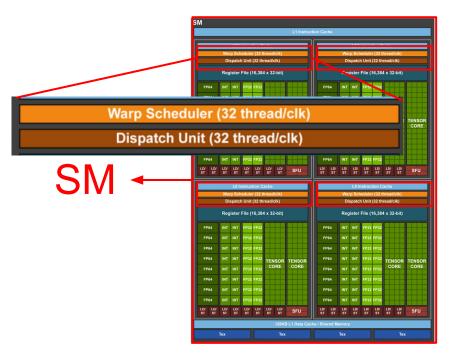
Existing tools apply high-level hotspot analysis

DrGPU Contribution

DrGPU

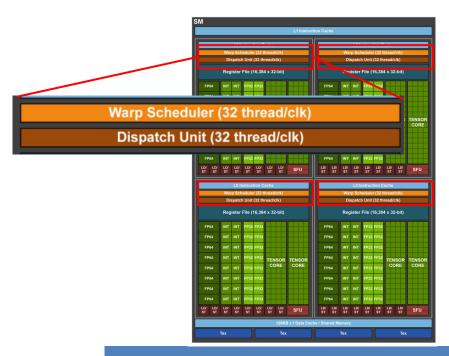
- tells you where GPUs waste on stalling by a top-down tree
- provides analysis and optimization guidance for non-experts

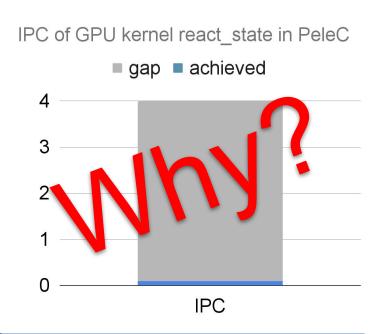
What are Bottlenecks of GPU?



1 instruction per cycle (IPC)
per warp scheduler per SM
=>
Ideal instruction per cycle is

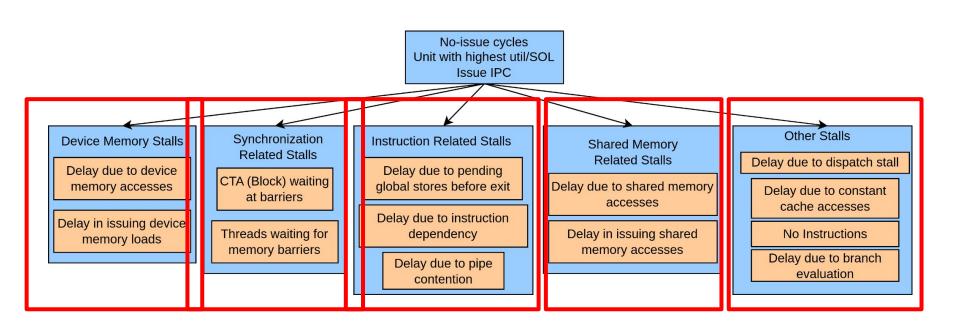
What are Bottlenecks of GPU?



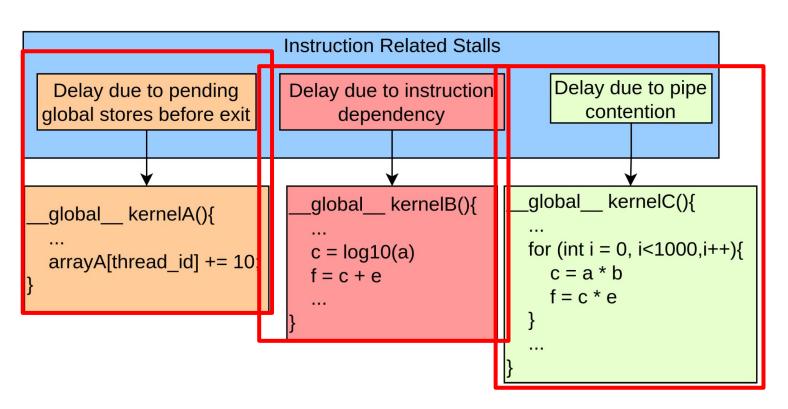


Gap is large between achieved IPC and ideal IPC!

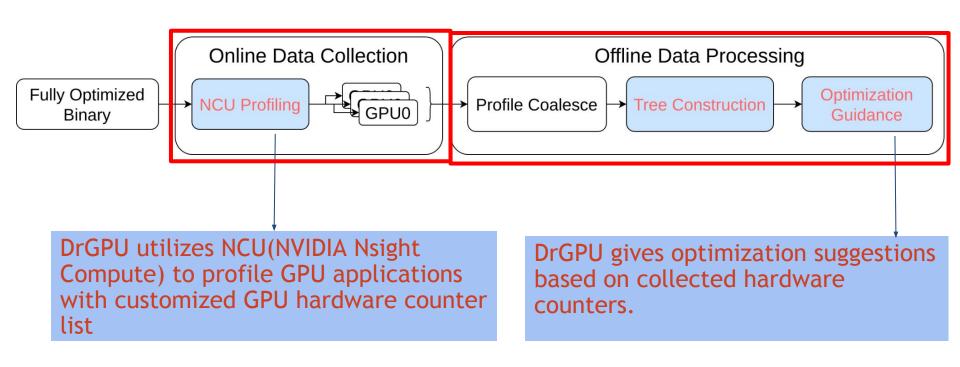
Categories of Stall Reasons



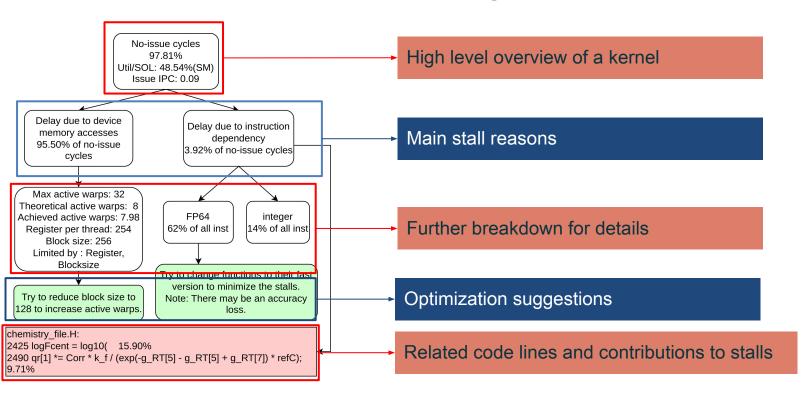
Instruction Related Stalls



DrGPU Overview



An example of Analysis Trees

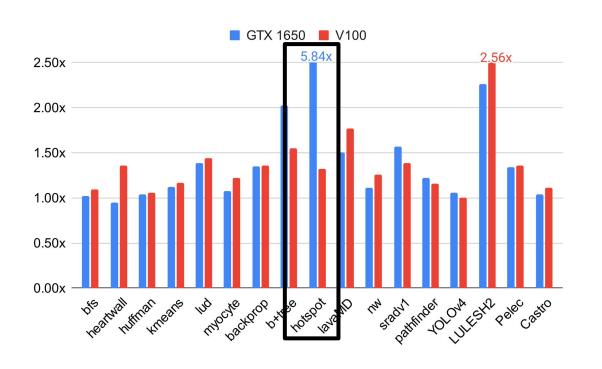


Evaluation Platforms

- GPU
 - V100 16GB
 - GTX 1650 4GB
- Applications
 - Rodinia benchmarks
 - YOLOv4 (Darknet)
 - LULESH2
 - PeleC
 - Castro

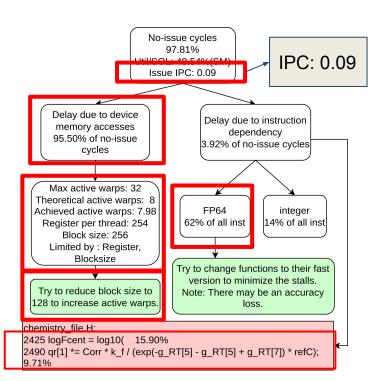
Application	Kernel	State	Optimization
bfs	Kernel	Long Scoreboard	Loop unrolling
heartwall	kernel	Wait	Loop unrolling
huffman	vlc_encode_kernel_sm64huff	Barriers	Restruct code
kmeans	kmeansPoint	Wait	Loop unrolling
lud	lud_diagonal	Wait/	Restruct code
		Short Scoreboard/ No instruction	
myocyte	solver_2	Short Scoreboard	Function spliting
		Math Pipe Throttle	Add use_fast_math
backprop	bpnn_layerforward_CUDA	Barrier	Remove unnecessary barriers
		Wait	Restruct code
b+tree	findRangeK	Long Scoreboard	Restruct code
		Barrier	Reduce blocksize
hotspot	calculate_temp	Wait	Remove inappropriate FP convertion
			Add use_fast_math
lavaMD	kernel_gpu_cuda	Long Scoreboard/Wait	Loop unrolling
		Wait	Replace speical FP functions
nw	needle_cuda_shared_1	Barriers	Remove unnecessary barriers
			Replace syncthreads with sync warp safel
sradv1	reduce	Short Scoreboard	Loop unrolling
		Barrier	Reduce blocksize
pathfinder	dynproc_kernel	Short Scoreboard	Replace shared memory with variables
		Wait	Remove unnecessary iterations
Darknet	im2col_gpu_kernel_ext	Wait	Loop unrolling
LULESH2	ApplyMaterialProperties AndUpdateVolume_kernel	Wait	Add use_fast_math
Pelec	react_state	Long Scoreboard	Increase occupancy
		Wait	Replace speical FP functions
Castro	trace_ppm	long scoreboard	Increase occupancy

Speedups with Optimization Guided by DrGPU



1.58X on GTX 1650

1.36X on V100



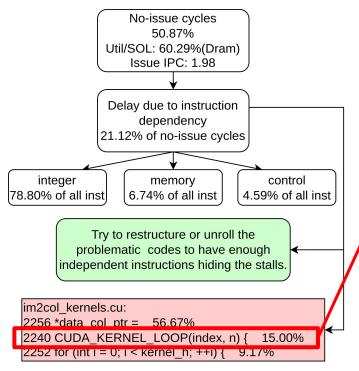
A portion of the analysis tree on GTX 1650

PeleC

Optimizations

- Set blocksize to 128.
- Replace functions to their faster version. e.g., log10 -> log10f (0.1% precision loss)
- 1.34X speedup on GTX 1650
- 1.36X speedup on V100

YOLOv4



A portion of the analysis Tree on GTX 1650

Optimization

- Loop unrolling
- 1.06X speedup on GTX 1650

Conclusions

We propose DrGPU, a novel top-down profiler for GPU kernels.

- > DrGPU quantifies stall cycles and decomposes them according to various hardware events for root causes.
- DrGPU generates performance analysis trees including source code location, root causes, and actionable guidance
- We optimized a number of applications with the insights provided by DrGPU with nontrivial speedups on both desktop and Summit NVIDIA GPUs
- Some of optimization suggestions proposed by DrGPU have been integrated to NVIDIA Nsight Compute

Code is available at: https://github.com/FindHao/drgpu

Thanks!